

K J SOMAIYA COLLEGE OF ENGINEERING, MUMBAI-77 (CONSTITUENT COLLEGE OF SOMAIYA VIDYAVIHAR UNIVERSITY)

ICR (Instantaneous Centre of rotation)



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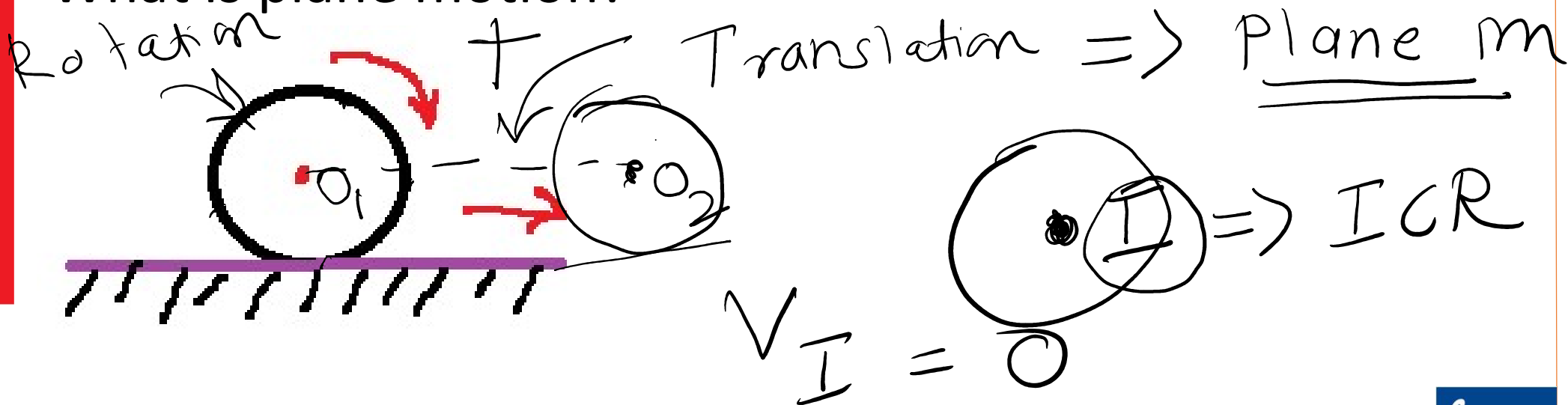
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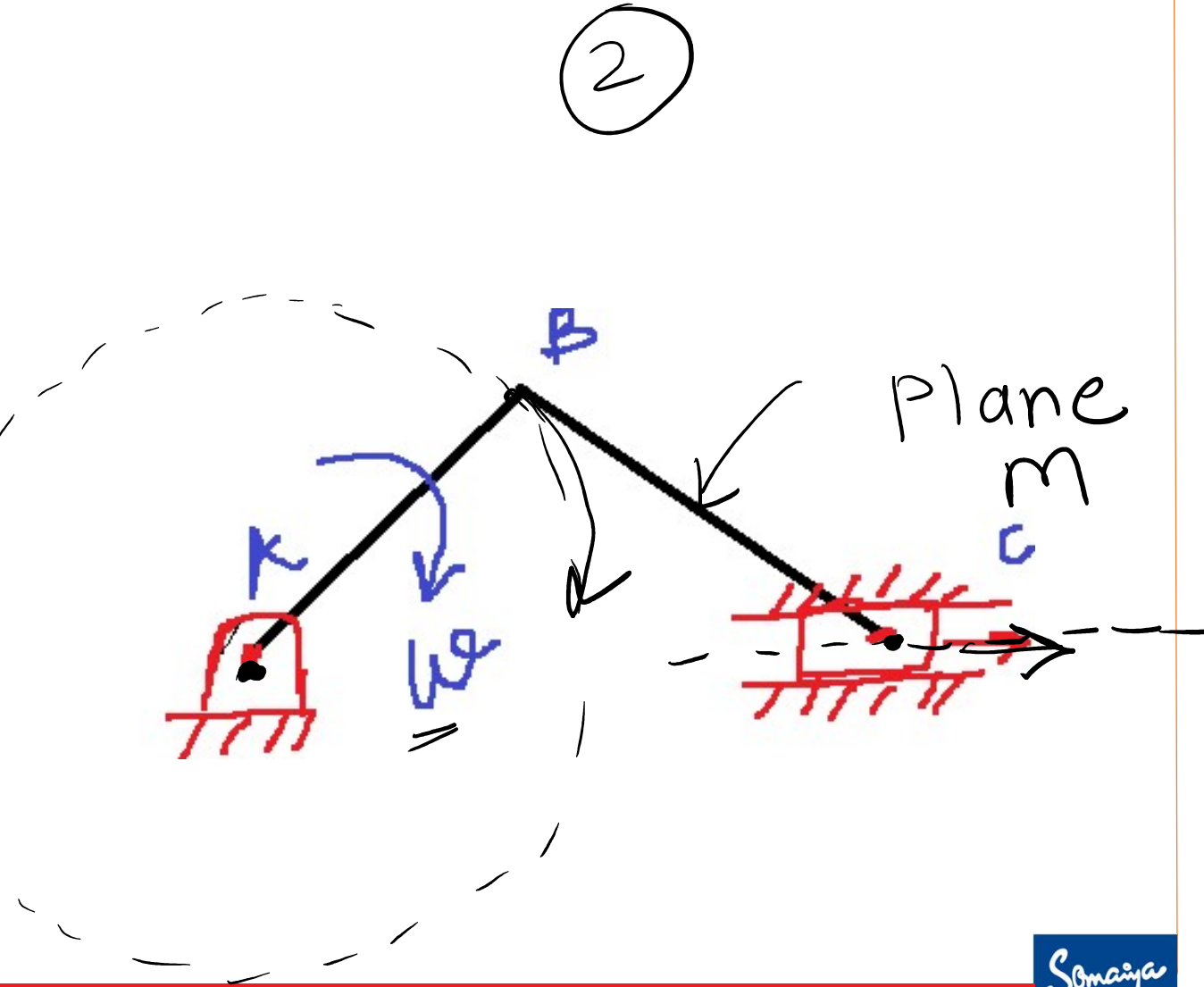
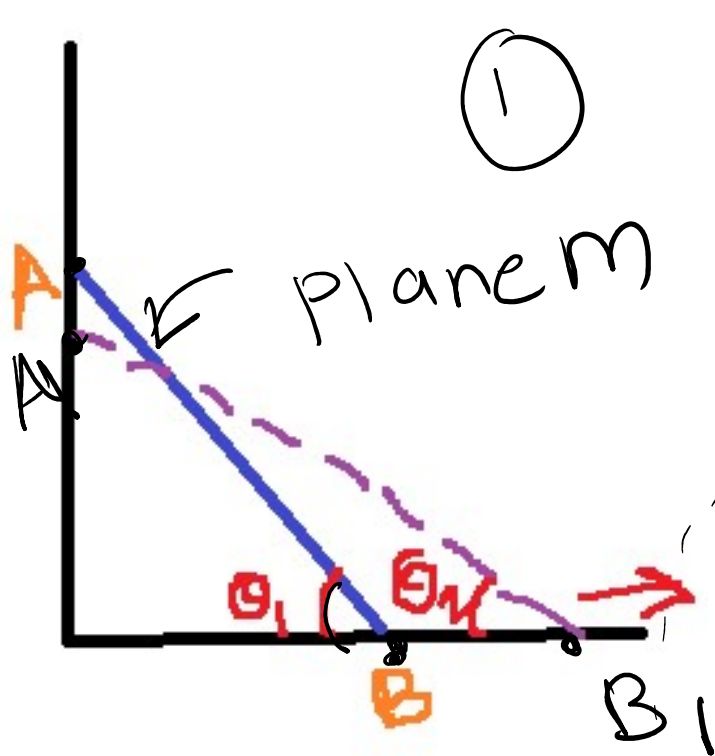
What is ICR?

Plane motion is the combination of rotation and translation. Such plane motion is converted into pure rotation about an arbitrary point. This point is called as ICR (Instantaneous Centre of rotation)

It is an imaginary point having zero velocity and its location is changing from instant to instant.

What is plane motion?





AB \curvearrowright
 BC - plane m

Location of ICR

$$\frac{AB}{BC}$$

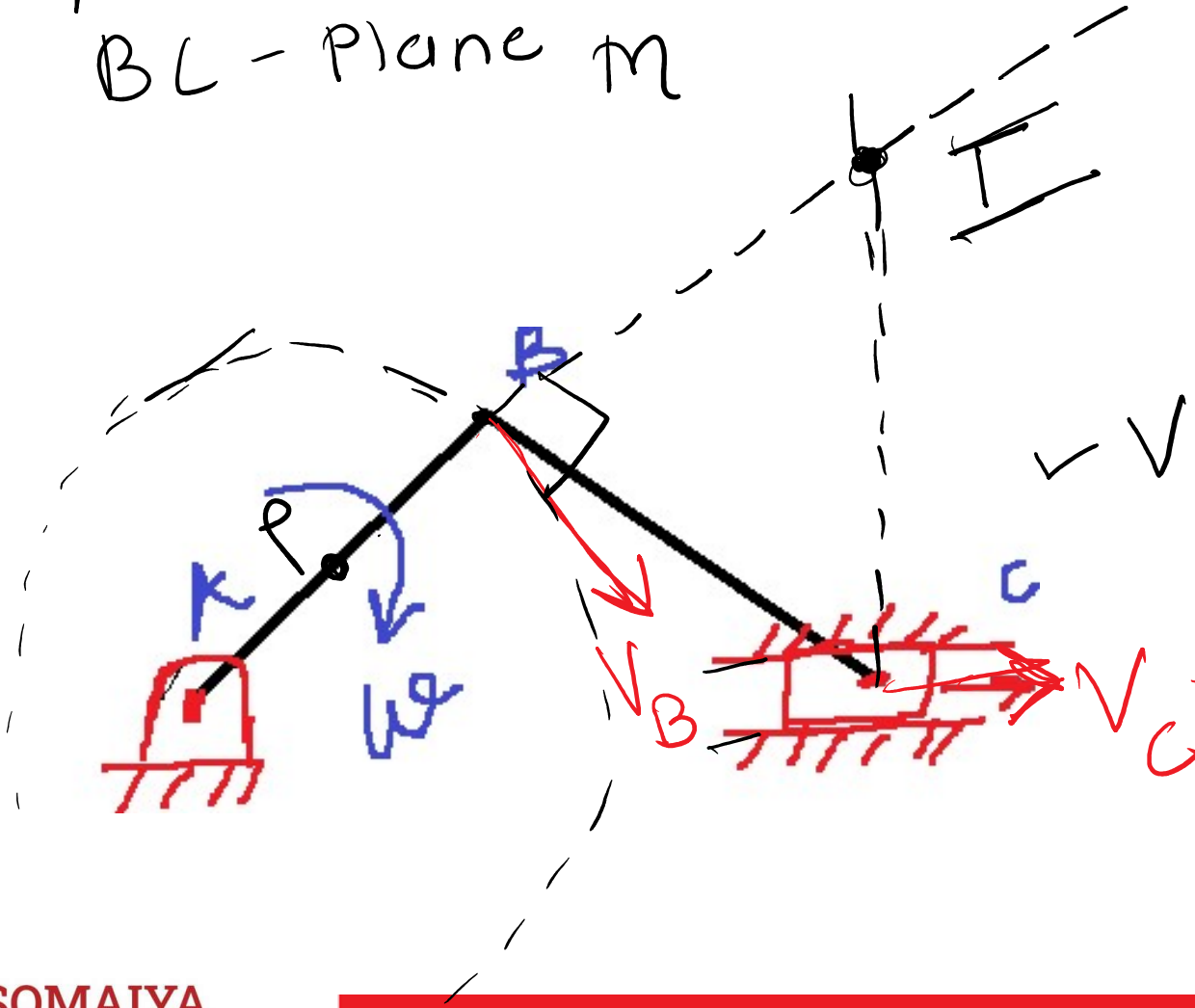
$$V = \gamma W$$

$$V_B = AB \times W_{AB}$$

$$\frac{BC}{BC}$$

$$V_B = I_B \times W_{BC}$$

$$V_C = I_C \times W_{BC}$$

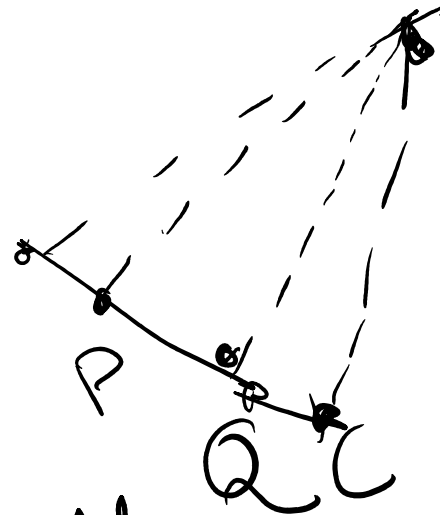


$$\underline{V}_Q = \underline{I}_Q \times \omega_{BC}$$

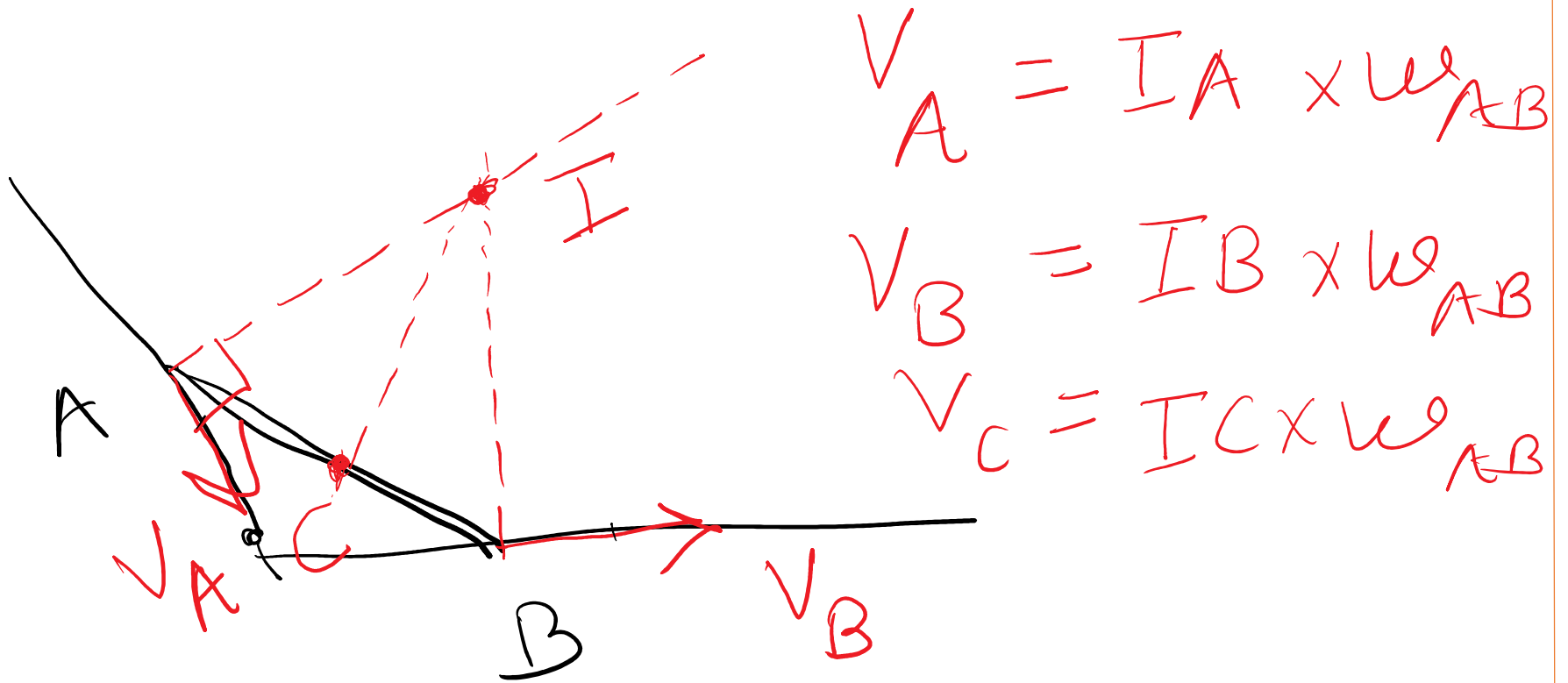
$$\underline{I} \quad \underline{V} = \underline{r} \omega$$

$$V_B = I_B \times \omega_{BC}$$

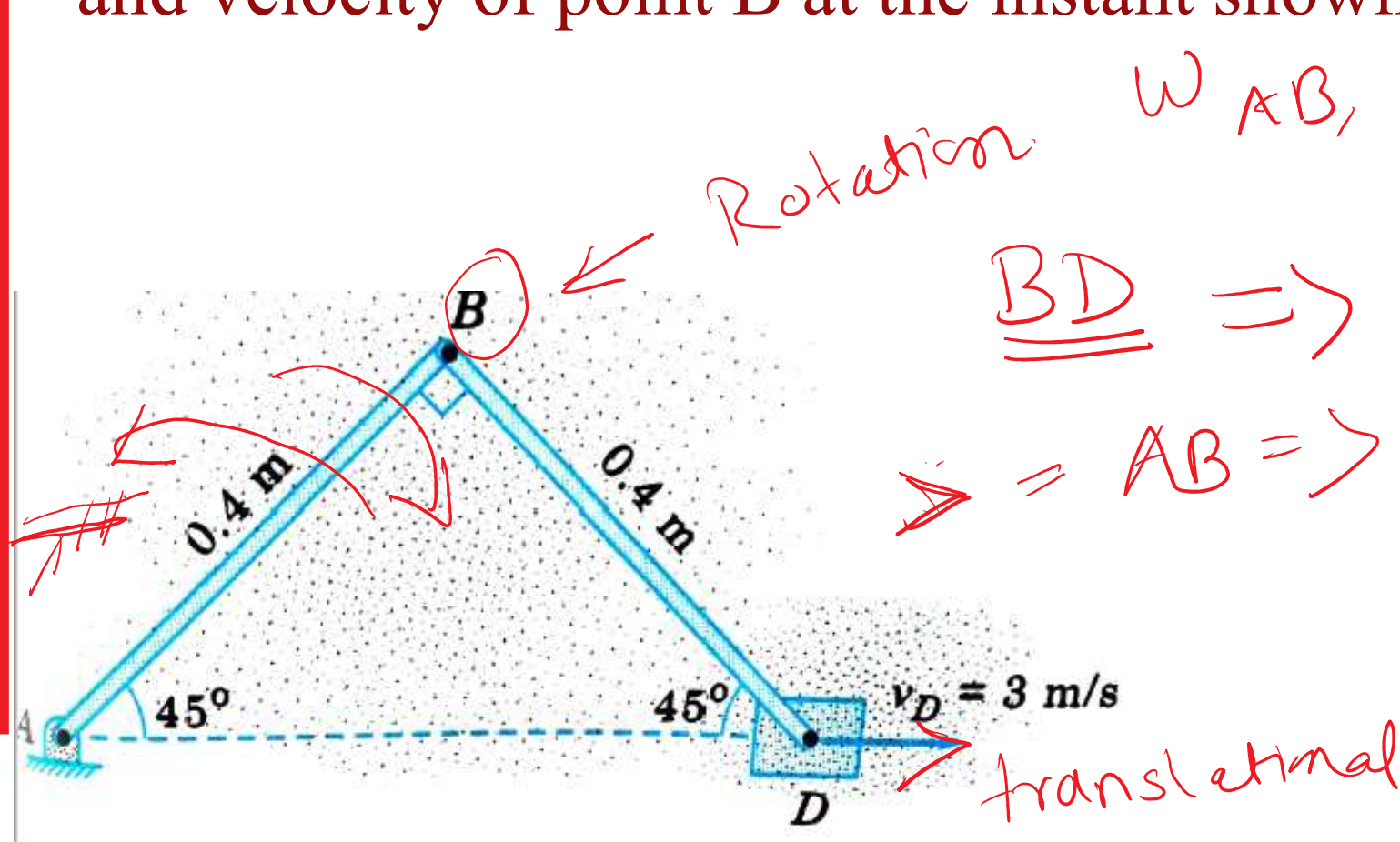
$$V_C = I_C \times \omega_{BC}$$



$$\underline{V}_P = \underline{I}_P \times \omega_{BC}$$



Determine the angular velocity of links AB and BD and velocity of point B at the instant shown



$\omega_{AB}, \omega_{BD} = ?$

BD => plane m

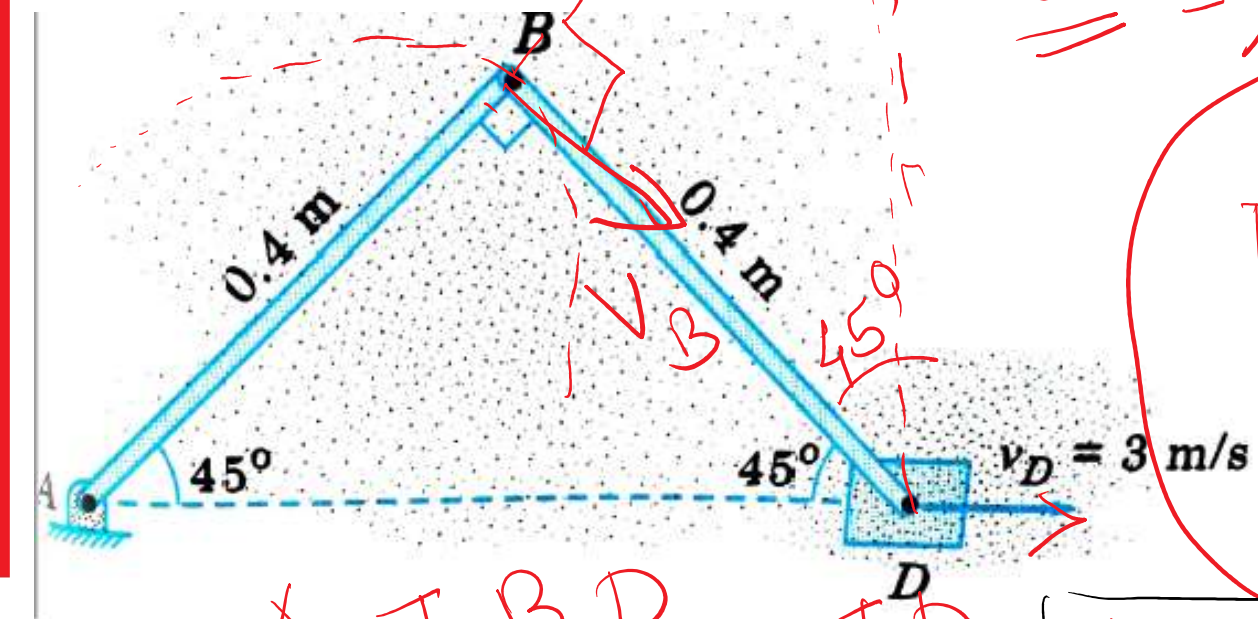
\Rightarrow AB => Rotation

translational

$$\begin{cases} I_D = 0.565 \text{ m} \\ I_B = 0.4 \text{ m} \end{cases} \begin{matrix} AB \\ BD \end{matrix}$$

I_B, I_D

$BD \Rightarrow v_B = I_B \times \omega_{BD}$



$v_D = I_D \times \omega_{BD}$

$\omega_{BD} = 5.38 \text{ /s}$

$\Delta IBD, I'D$

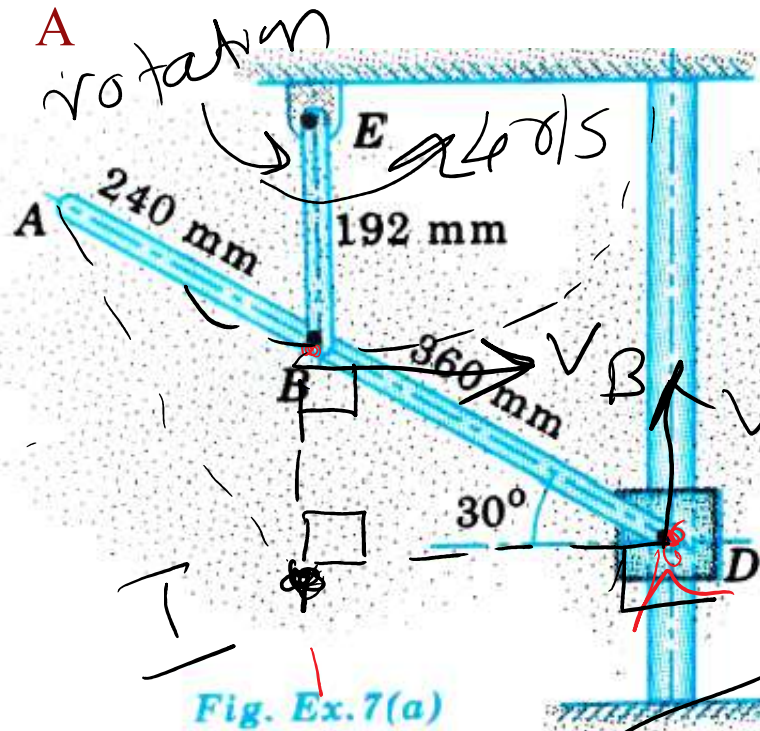
$v_B = 2.124 \text{ m/s}$

link AB ✓

$$\underline{V}_B = \underline{AB} \times \omega_{AB}$$

$$\underline{\omega}_{AB} = 5.3 \text{ rad/s}$$

Link EB in the mechanism has angular velocity of 4 rad/sec in CCW direction. Calculate – angular velocity of rod AD, velocity of collar D, velocity of point A



$$V_A = ? \quad V_D = ? \quad \omega_{AD} = ?$$

$$EB \Rightarrow V_B = EB \times \omega_{EB}$$

$$= V_B = 0.768 \text{ m/s}$$

$$AD \Rightarrow V_B = IB \times \omega_{AD}$$

$$IB = 0.18 \text{ m}, \quad ID = 0.83 \text{ m}$$

$$\omega_{AD} = 4.26 \text{ rad/s}$$

$\triangle IAD$

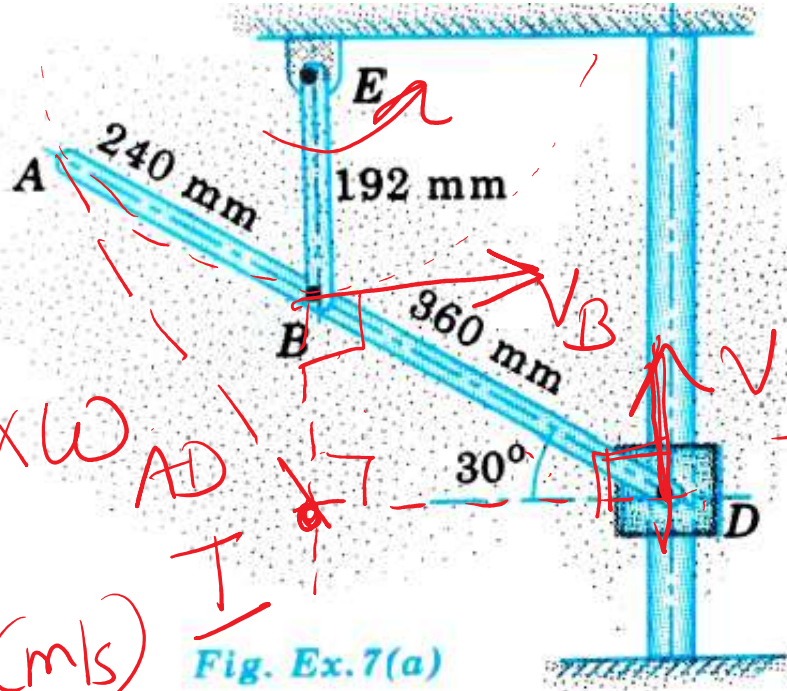
$$IA^2 = ID^2 + AD^2 - 2IA \cdot AD \cos 30^\circ$$

$$IA = 0.365 \text{ m}$$

$$V_A = IA \times \omega_{AD} = 1.556 \text{ m/s}$$

$$V_D = ID \times \omega_{AD}$$

$$V_D = 1.33 \text{ m/s}$$



$$\underline{EB} \Rightarrow V_B = EB \times \omega_{ED}$$

$$\omega_B = 192 \times 4 = \text{mm/s}$$

$$V_B = \underline{IB} \times \omega_{AD}$$

$$\omega_{AD} = \text{r/s}$$

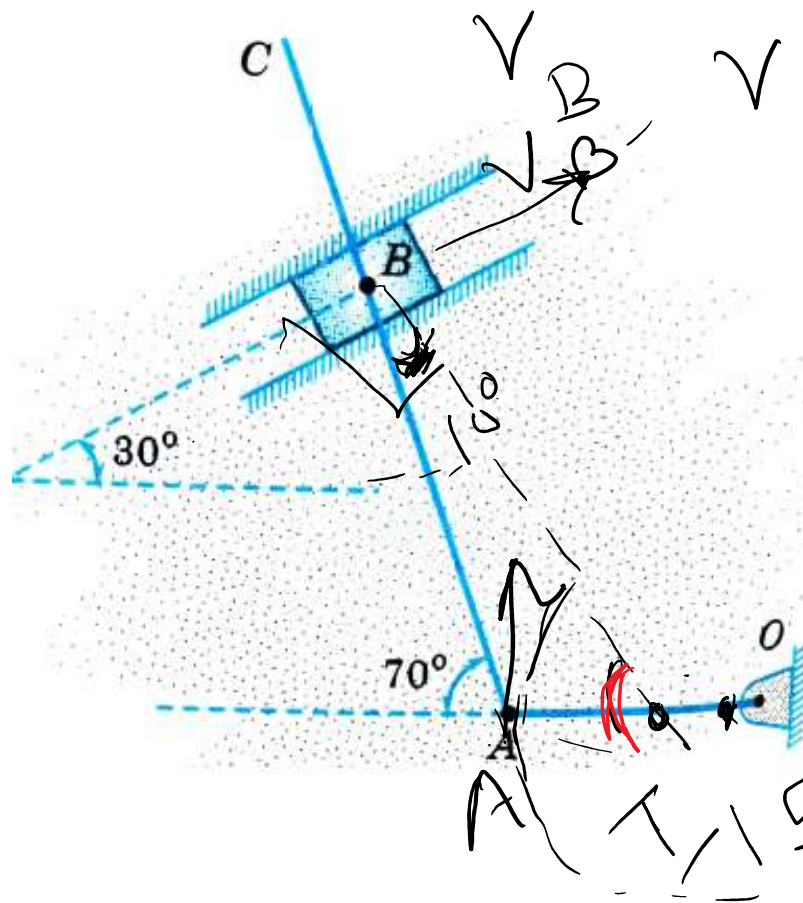
$$V_A = \underline{IA} \times \omega_{AD}$$

$$V_A = \text{(m/s)} \times \underline{IB}$$

$$\underline{IB} =$$

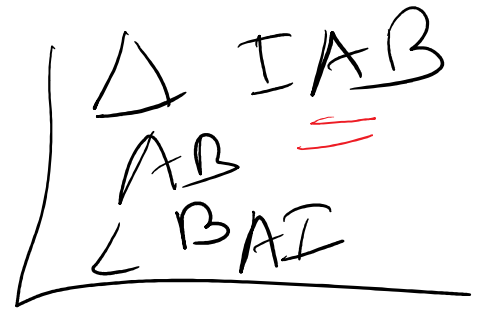
$$\underline{ID} =$$

Angular velocity of rod OA is 15 rad/sec CCW direction, length of OA = 200 mm, AB = 400 mm and BC = 150 mm. Locate ICR



$v_C = ?$

$\omega_{OA} = 15 \text{ rad/s}$



$v_A = OA \times \omega_{OA}$

$v_A = IA \times \omega_{ABC}$

$\frac{IA}{\sin 10} = \frac{IB}{\sin 110} = \frac{AB}{\sin 60}$

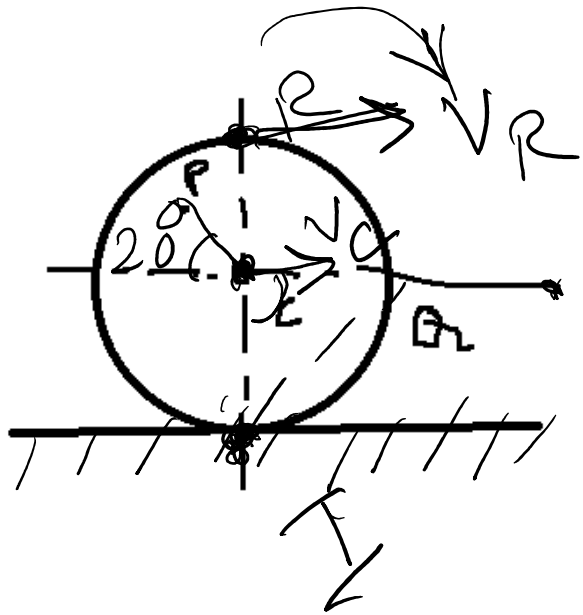
$$V_A = 3 \text{ m/s}$$

$$I_A = 0.08 \text{ m}$$

$$I_B = 0.434 \text{ m}$$

$$V_B = I_B \times \omega_{ABC} \quad (\omega_{ABC} = 37.41 \text{ rad/s})$$
$$= 16.24 \text{ m/s}$$

$$V_C = I_C \times \omega_{ABC}$$
$$= 21.8 \text{ m/s}$$

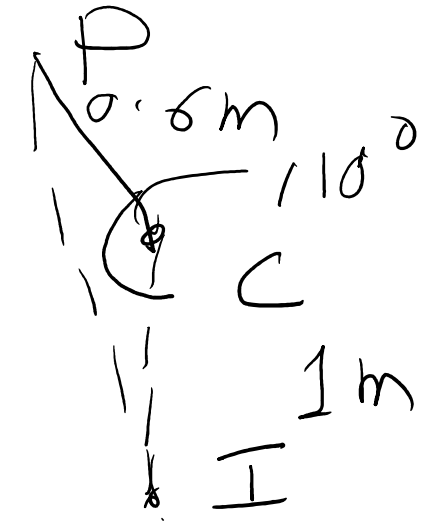


$$\omega = ?$$

$$v = r\omega$$

$$\omega = \frac{v}{r}$$

$$\omega = \frac{v_C}{r_{IC}} = \frac{v_P}{r_{IP}} = \frac{v_Q}{r_{IQ}} = \frac{v_R}{r_{IR}}$$



$$r_{IR} = 2m$$

$$v_R = 8 \text{ m/s} \quad \omega = \frac{4}{1} = 4 \text{ rps}$$

$$v_Q = 5.615 \text{ m/s}$$

$r_{IQ} = \dots$



A ladder AB of 6 m long resting against a vertical wall at A and horizontal ground at B (with an inclination of 30° with horizontal) . If the end B of the ladder is pulled towards right with a constant velocity of 4 m/s, find: 1) ICR location, 2) angular velocity of ladder at this instant, 3) velocity of end A, 3) velocity components of midpoint of the ladder

